



Time-Varying and Random Environment Matrix Models



Shripad TULJAPURKAR ("Tulja") who extensively developed the theory of population models in random environment

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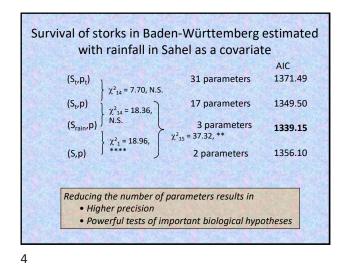
## When the model matrix varies from year to year....

## Time-Varying Models:

- ... in a known fashion over finite time window
- Recorded sequence of bad and poor years
- Relationship between demographic parameter and env. covariate
- MAIN AIM: model a known trajectory (retrospective)

## **Random Environment:**

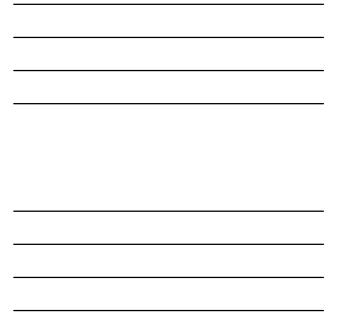
- ... in a random fashion over a finite or infinite time window
- Projection of relationship between parameter and env. covariate
- Unexplained year-to-year (environmental) variation
- MAIN AIM: projection, asymptotic behavior (prospective)

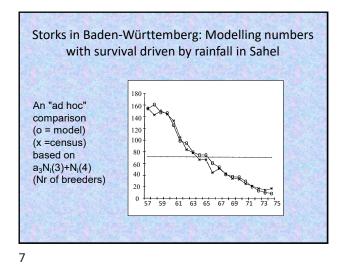




Survival of storks in Baden-Württemberg estimated with rainfall in Sahel as a covariate 0.9 8.0 survival Estimated : 0.4 0.3 1957 1959 1961 1963 1965 1967 1969 1971 Model  $(S_{rain}, p)$  $(S_t,p)$ (S,p) AIC 1349.50 1339.15 1356.10  $\log (S / (1 - S)) = a + b rain$ 

							ling number n Sahel
Year	57	58		i	i+1		74
Rain	x <sub>57</sub>	x <sub>58</sub>		x <sub>i</sub>	x <sub>i+1</sub>		x <sub>75</sub>
Rain Survival Matrix	ф <sub>57</sub>	ф <sub>58</sub>		φi	φ <sub>i+1</sub>		ф <sub>75</sub>
Matrix	M <sub>57</sub>	M <sub>58</sub>		Mi	M <sub>i+1</sub>		M <sub>75</sub>
	s obtaine <sub>56</sub> based	ed by a	« ti age	me-v	arying	matri	x model »





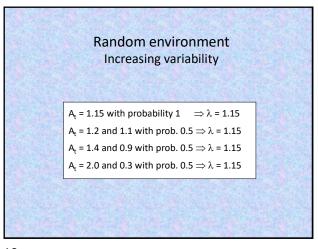


Likelihood based approach to time-varying models: State-space model Greater snow goose



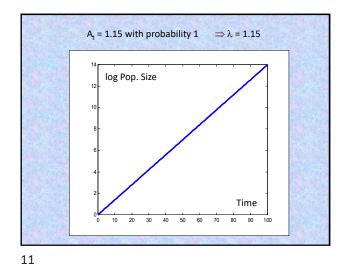
Random Environment the scalar exponential model (no stage/age classes)

$$\begin{split} n(t) = &A_t \; n(t\text{-}1) \\ A_t \; \text{random scalar (i.i.d.) , with } E(A_t) = &\lambda \\ E(n(t) \; / \; n(t\text{-}1) \;) = &\lambda \; n(t\text{-}1) \\ E(n(t) \; / \; n(0) \;) \; = \; &\lambda^t \; n(0) \end{split}$$

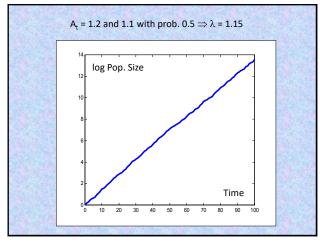




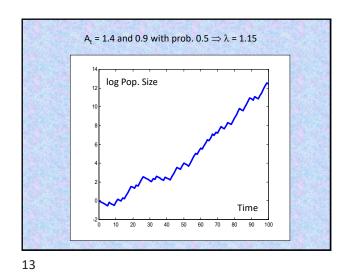




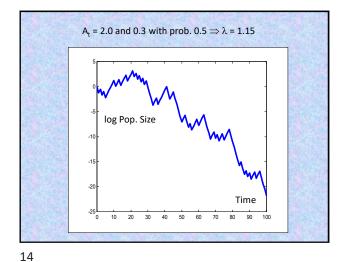




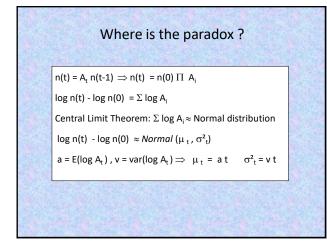


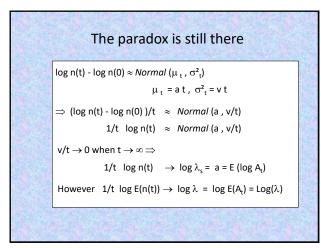




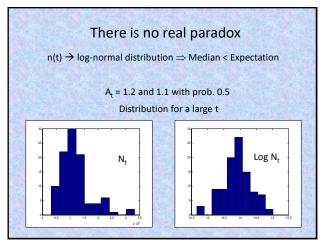




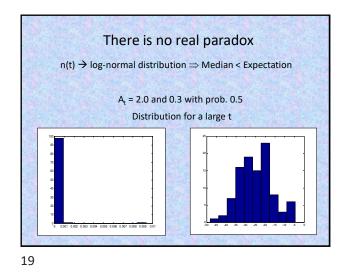




1		EXPECTED	MOST PROBABL
A <sub>t</sub> values	λ	log λ	$\log \lambda_s$
1.15	1.15	0.1398	0.1398
1.2 1.1	1.15	0.1398	0.1388
1.4 0.9	1.15	0.1398	0.1156
2.0 0.3	1.15	0.1398	-0.2554



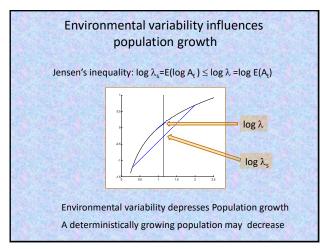




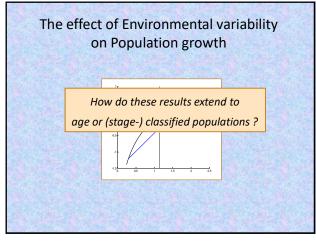


**There is no real paradox** A few trajectories with large growth rate keep the expected growth rate equal to  $\log \lambda = \log E(A_t)$ Most probable trajectories are concentrated around  $\log \lambda_s = E (\log A_t)$  (more and more when  $t \rightarrow \infty$ )

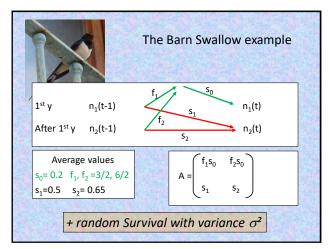
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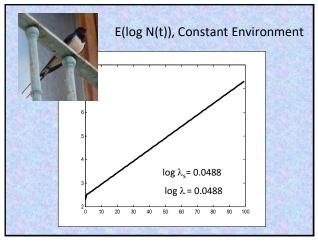




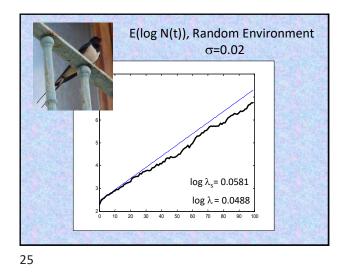






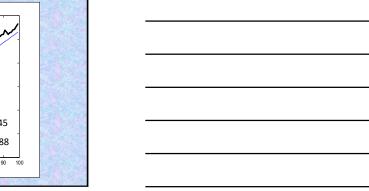


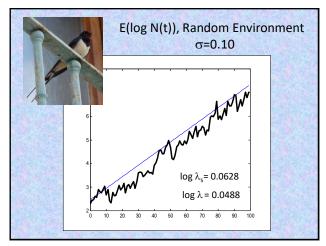




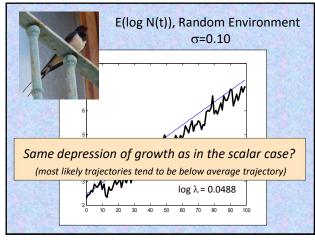


E(log N(t)), Random Environment  $\sigma$ =0.05

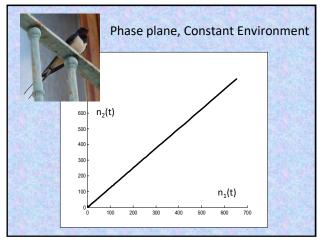




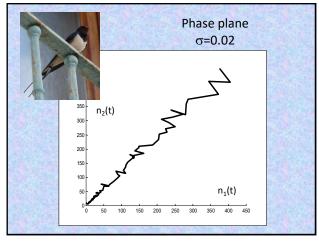




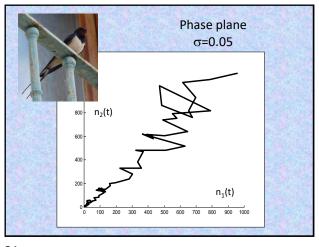






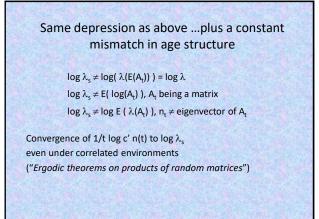


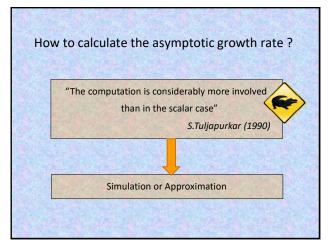


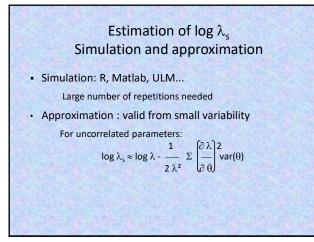












7		E	Estimation of log $\lambda_s$ Approximation					
1				APPROXIMATE				
	σ	λ	$\log \lambda$	$\log \lambda_s$				
	0.00	1.05	0.0488	0.0488				
	0.01	1.05	0.0488	0.0486				
	0.05	1.05	0. 0488	0.0442				
	0.10	1.05	0.0488	0.0304				



